

Sample slides and recommendations

- **Font type:** Sans
- **Font size for content text and formulae:** 18 pt and above
- **Font size for title (Title slide):** 36 pt and above
- **Font size for figure captions:** 16 pt and above
- **Maximum no. of slides (excluding Title, Reference and Thank you):** 6
- **Maximum size of file:** 5 MB

You can
put
logos
here as
well

Title

Authors

Affiliation

Biot-Savart law

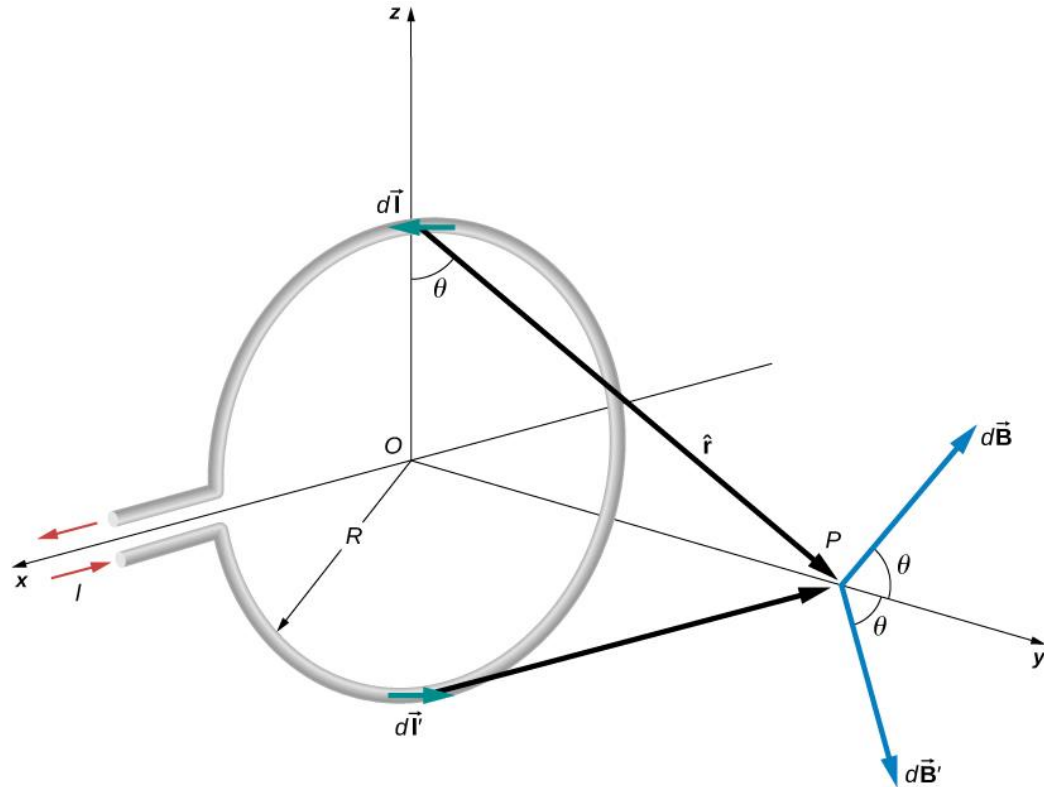


Figure: Magnetic Field of a Current Loop.

Authored by: OpenStax College.

Located at: <https://openstax.org/books/university-physics-volume-2/pages/12-4-magnetic-field-of-a-current-loop>.

In physics, specifically electromagnetism, the **Biot–Savart law** is an equation describing the magnetic field generated by a constant electric current. It relates the magnetic field to the magnitude, direction, length, and proximity of the electric current.

$$dB = \frac{\mu_0 I dl \sin \theta}{4\pi r^2}$$



Figure: Apparatus for the study of Biot-Savart's Law
(Source: https://holmarc.com/biot_savarts_law.php)

Spherical Polar Coordinates

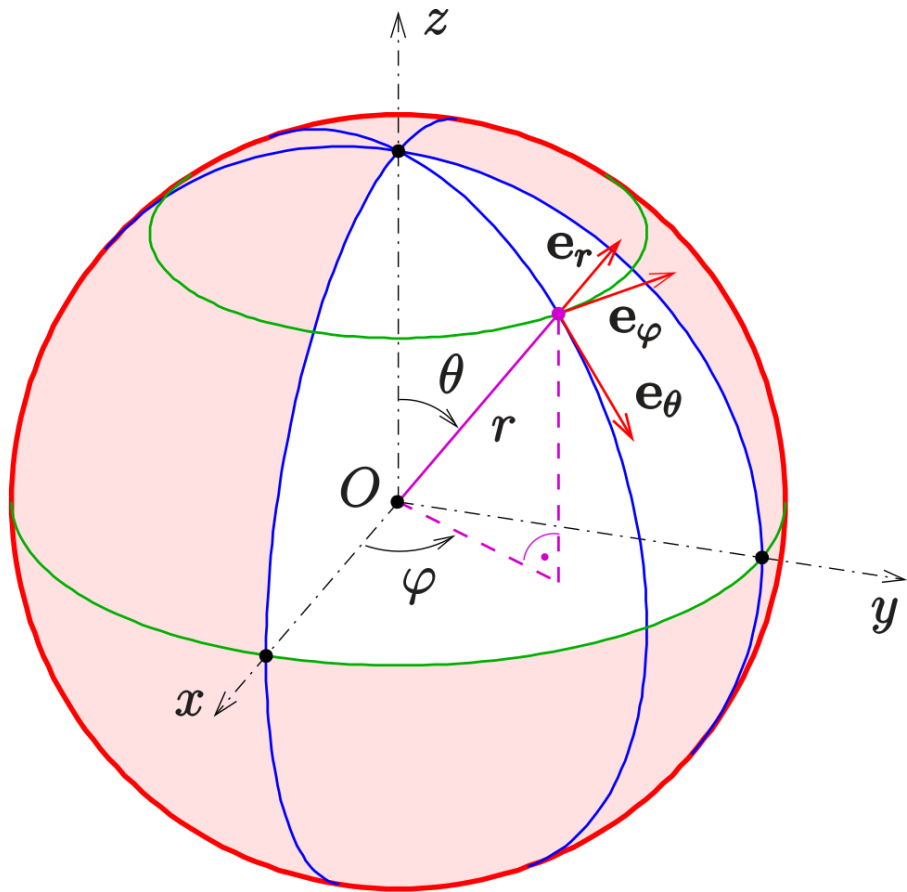


Figure: Unit vectors in spherical coordinates

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via Wikimedia Commons)

Wednesday, 07-06-2023

The line element for an infinitesimal displacement from (r, ϑ, φ) to $(r + dr, \vartheta + d\vartheta, \varphi + d\varphi)$ is

$$d\mathbf{r} = dr \hat{\mathbf{r}} + r d\theta \hat{\boldsymbol{\theta}} + r \sin \theta d\varphi \hat{\boldsymbol{\varphi}},$$

where

$$\hat{\mathbf{r}} = \sin \theta \cos \varphi \hat{\mathbf{x}} + \sin \theta \sin \varphi \hat{\mathbf{y}} + \cos \theta \hat{\mathbf{z}},$$

$$\hat{\boldsymbol{\theta}} = \cos \theta \cos \varphi \hat{\mathbf{x}} + \cos \theta \sin \varphi \hat{\mathbf{y}} - \sin \theta \hat{\mathbf{z}},$$

$$\hat{\boldsymbol{\varphi}} = -\sin \varphi \hat{\mathbf{x}} + \cos \varphi \hat{\mathbf{y}}$$

are the local orthogonal unit vectors in the directions of increasing r , ϑ , and φ , respectively, and $\hat{\mathbf{x}}$, $\hat{\mathbf{y}}$, and $\hat{\mathbf{z}}$ are the unit vectors in Cartesian coordinates. The linear transformation to this right-handed coordinate triplet is a rotation matrix,

$$R = \begin{pmatrix} \sin \theta \cos \varphi & \sin \theta \sin \varphi & \cos \theta \\ \cos \theta \cos \varphi & \cos \theta \sin \varphi & -\sin \theta \\ -\sin \varphi & \cos \varphi & 0 \end{pmatrix}.$$

Biot-Savart law

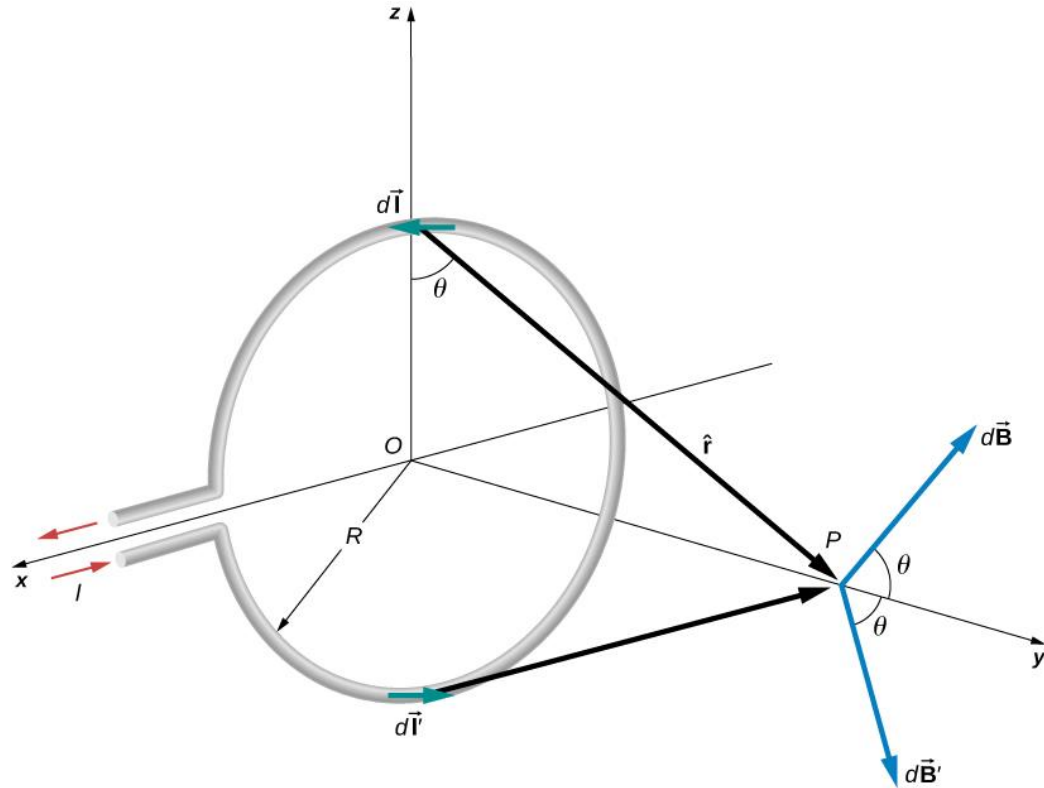


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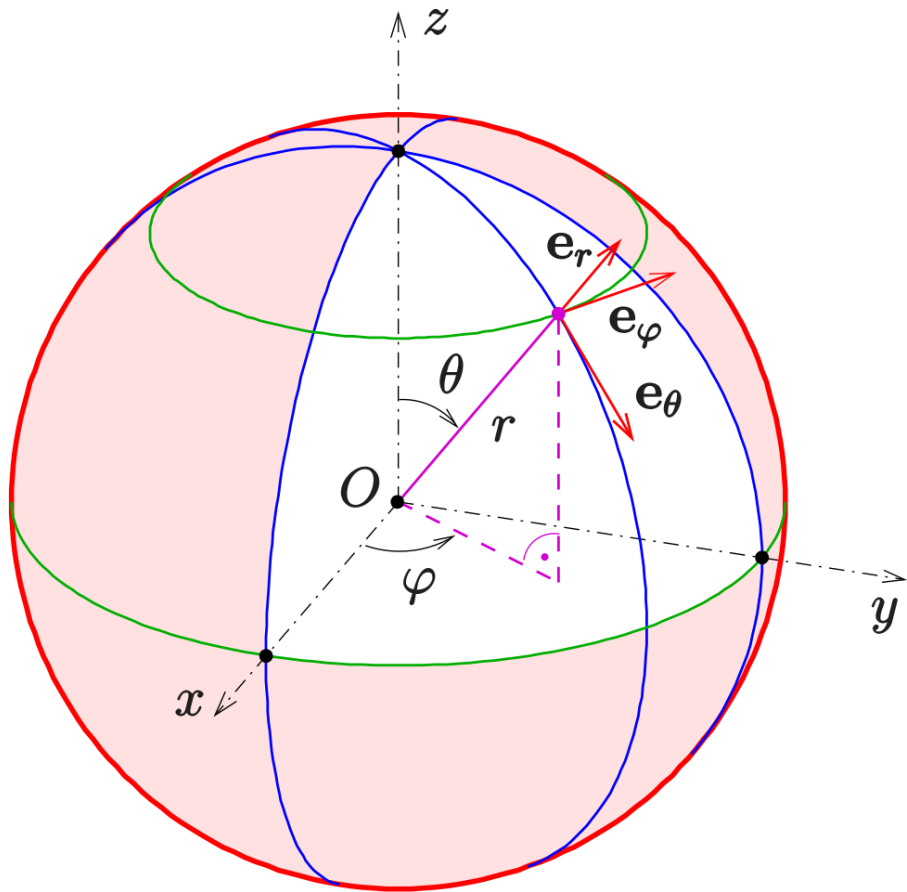


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Biot-Savart law

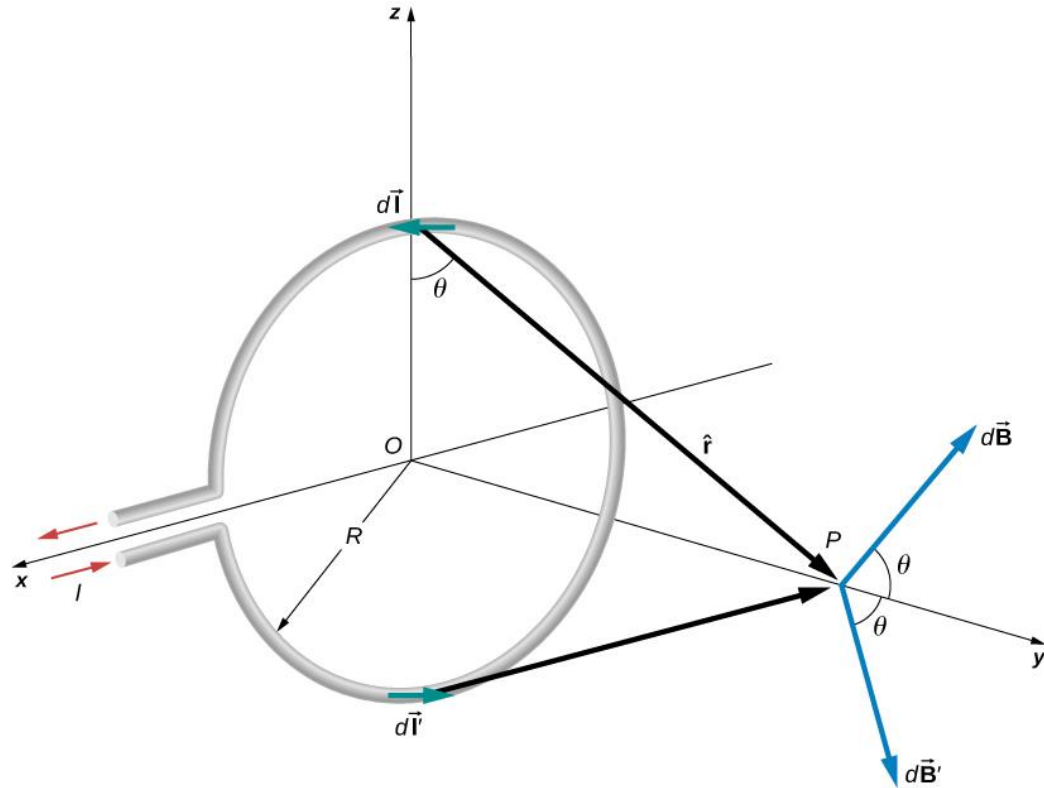


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References

1. Planck Collaboration et al. In: A&A 594 (2016), A13.
2. Laura Baudis. In: Physics of the Dark Universe 1.1 (2012), pp. 94 –108.
3. CUORE Collaboration et al. In: arXiv e-prints, arXiv:1801.05403 (2018), arXiv:1801.05403.
4. A. Kumar et al. In: Pramana 88.5 (2017), p. 79.
5. F. P. An et al. In: Phys. Rev. Lett. 118 (25 2017), p. 251801.
6. S. Agostinelli

Acknowledgements

We are thankful to so and so. We acknowledge the help from ‘this’ funding agency etc.

Thank you